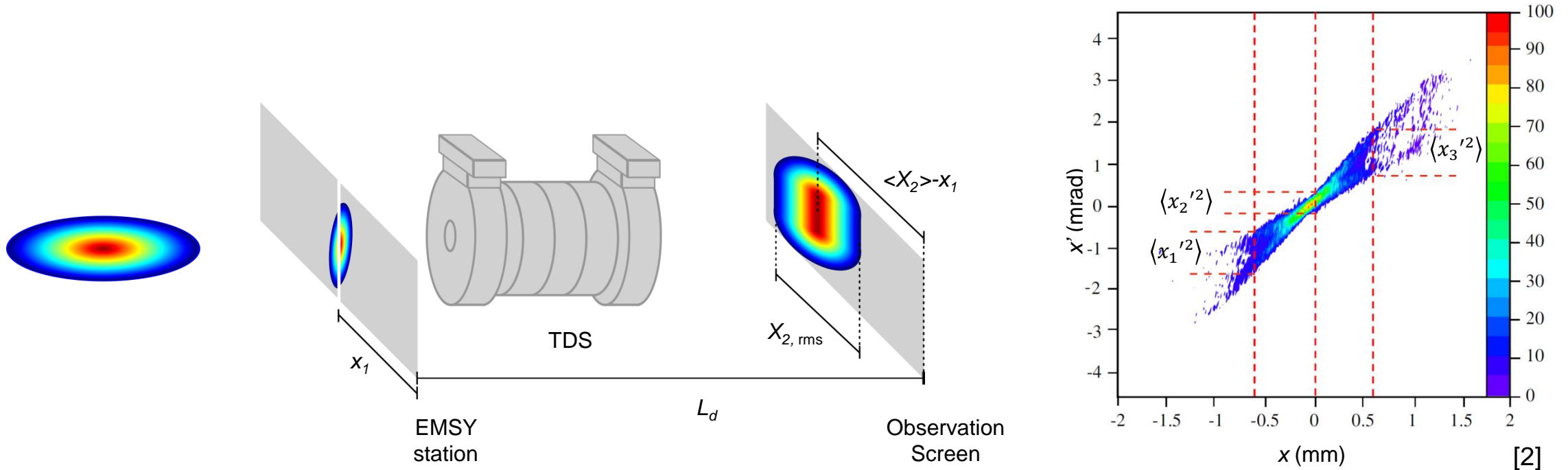


Further analysis of stat. error calculation for emittance calculation

Raffael Niemczyk, Zeuthen, February 14th 2018

Recap: Slit Scan Method

Slit-Scan-based slice emittance measurements



- > Cut out **emittance-dominated beamlets** from **space charge-dominated beam** with a slit
 - Measure the **size**, **position** and **intensity** of each beamlet on screen
- > Reconstruct the phase space at slit position

- Emittance via $\epsilon = \beta\gamma \frac{\sigma_x}{\sqrt{\langle x^2 \rangle}} \sqrt{\langle x_0'^2 \rangle \langle x_0^2 \rangle - \langle x_0 x_0' \rangle^2}$

[2] S. Rimjaem et al., Nucl. Instr. Meth. Phys. Res. A **671**, 62 – 75 (2012).

Recap: What we've had until now

Result from K'n'K seminar on Friday, January 18th

- > Emittance uncertainty, calculated via Gaussian error propagation (neglecting covariance) gives high stat. error

$$\Delta\epsilon = \sqrt{\left(\frac{d\epsilon}{dV_x} \Delta V_x\right)^2 + \left(\frac{d\epsilon}{dV_p} \Delta V_p\right)^2 + \left(\frac{d\epsilon}{dCov} \Delta Cov\right)^2}$$

Gives ~ 34 % error for data looked at

- > RMS 'error' from several-times calculated emittance is small and reasonable
 - > Reconstructing ten phase spaces, first from the first image at every slit position, second from second image etc.
 - > Calculating the geom. emittance ten times
 - > Emittance = mean(ten emittances), Emittance error = rms(ten emittances)
 - > Gives ~ 3% error for data looked at

Recap: What was suggested

Result from K'n'K seminar on Friday, January 18th

1. Fourth-order moment is uncertainty of variance, see [1]
2. Include correlation terms in Gaussian error propagation
3. Calculate rms value of ten emittances as error, but put phase spaces together differently

		Number of taken image				
		1	2	3	4	5
Slit Position	1	Green	Red	Grey	Grey	Grey
	2	Green	Grey	Red	Grey	Grey
	3	Green	Grey	Grey	Red	Grey
	4	Green	Grey	Grey	Grey	Red



One way to assemble phase space



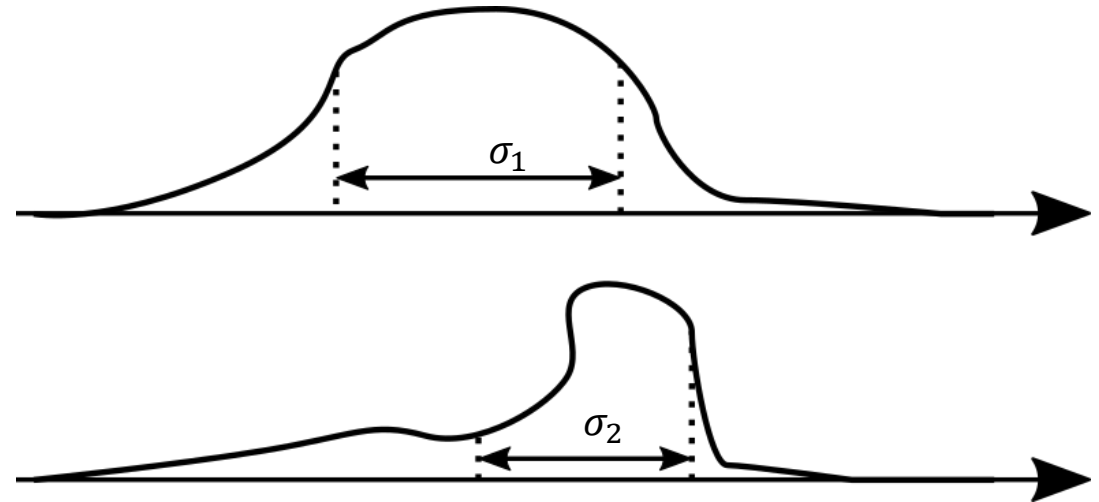
Another way to assemble phase space

[1] M. G. Kendall, *The advanced theory of statistics*, Vol. 1, 4th edition (1997)

Fourth-order as uncertainty:

See M. G. Kendall *The advanced theory of statistics, Vol. 1, 4th edition*

- > We are interested in variance, i.e. 2nd-order moment
 - > Variance as angular spread and beam size (of the phase space)
- > It's uncertainty is 4th-order moment, hence we use this as uncertainty
- > But: This uses only **one** measurement, not all distributions
 - > This gives you impossibly **statistical** error



Side note: Relative statistical errors of beam moments were small, hence another calculation of these errors wouldn't reduce the stat. error of the emittance

[1] M. G. Kendall, *The advanced theory of statistics, Vol. 1, 4th edition* (1997)

Gaussian error propagation


Adding correlation terms to the Gaussian error propagation formula

- > The 'standard' Gaussian error propagation (EP) goes like

$$\Delta\epsilon = \sqrt{\sum_i \left(\frac{\partial\epsilon}{\partial x_i} \sigma_i\right)^2} = \sqrt{\left(\frac{d\epsilon}{dVx} \Delta Vx\right)^2 + \left(\frac{d\epsilon}{dVp} \Delta Vp\right)^2 + \left(\frac{d\epsilon}{dCov} \Delta Cov\right)^2}$$

- > This however ignores **correlation** between different terms

$$\epsilon_{\text{geom}} = \sqrt{Vx * Vp - Cov^2}$$

- > General EP is $\Delta\epsilon = \sqrt{\sum_i \left(\frac{\partial\epsilon}{\partial x_i} \sigma_i\right)^2 + \sum \sum_{i \neq j} \frac{\partial\epsilon}{\partial x_i} \frac{\partial\epsilon}{\partial x_j} \sigma_{ij}}$  Correlation between inputs, not the same as covariance!!

- > This yields in a smaller statistical error, 24.2 % instead of 34.0 % (neglecting correlation)
- > Still a quite high statistical error

[1] K. O. Arras, *An Introduction To Error Propagation [...]*, Technical Report <http://srl.informatik.uni-freiburg.de/papers/arrasTR98.pdf> (visited 2019-04-02)

Reassembling the phase spaces

Do different reconstructions of the phase space and compare the results

- > Five different ways to reconstruct the phase space, see right
- > Calculate statistical error as

$$\Delta\epsilon = \text{rms}(\epsilon_i - \text{mean}(\epsilon_i))$$

		Emittance	Error
Reconstruction	1	3.96 μm	0.14 μm
	2	3.96 μm	0.15 μm
	3	3.96 μm	0.15 μm
	4	3.96 μm	0.15 μm
	5	3.96 μm	0.15 μm

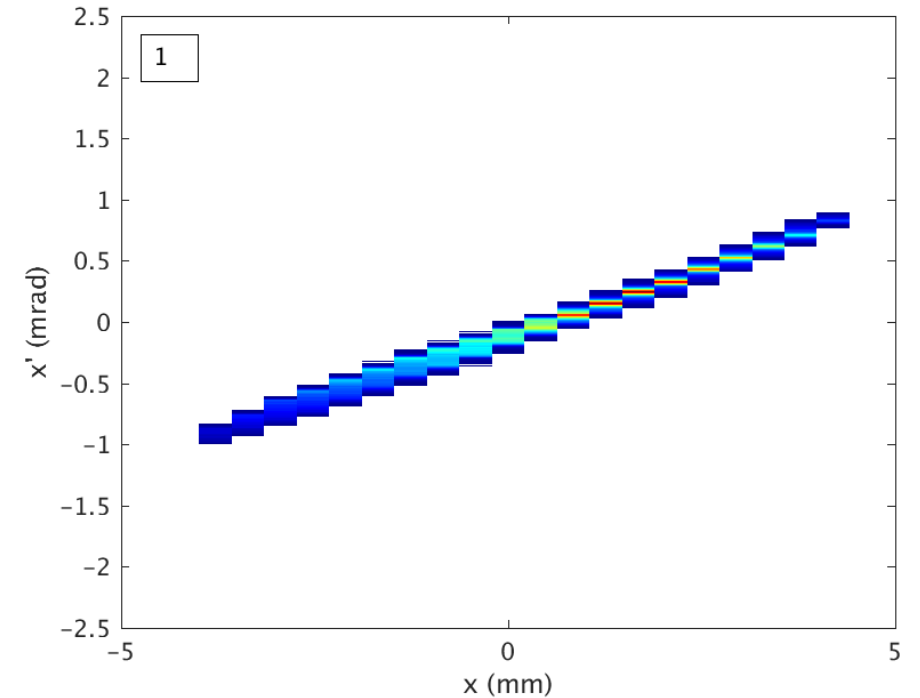
		Number of taken image				
		1	2	3	4	5
Slit Position	1	Green	Red			
	2	Green		Red		
	3	Green			Red	
	4	Green				Red

		Number of taken image				
		1	2	3	4	5
Slit Position	1	Blue	Magenta	Yellow		
	2		Blue	Magenta		Yellow
	3		Blue		Magenta	Yellow
	4		Blue		Magenta	Yellow
						Magenta

Let's look on the data

How does the phase spaces in this example look like?

- Data was taken on 2018-11-24T0639_XFEL_beam_studies
- Ten reconstructed phase spaces shown right
- Only $\Delta\epsilon = \text{rms}(\epsilon_i - \text{mean}(\epsilon_i))$ gives reasonable error
- Different reconstruction methods don't change error significantly
- Other errors are far too big



Gaussian error propagation neglecting correlations: $\frac{\Delta\epsilon}{\epsilon} = 34.0 \%$

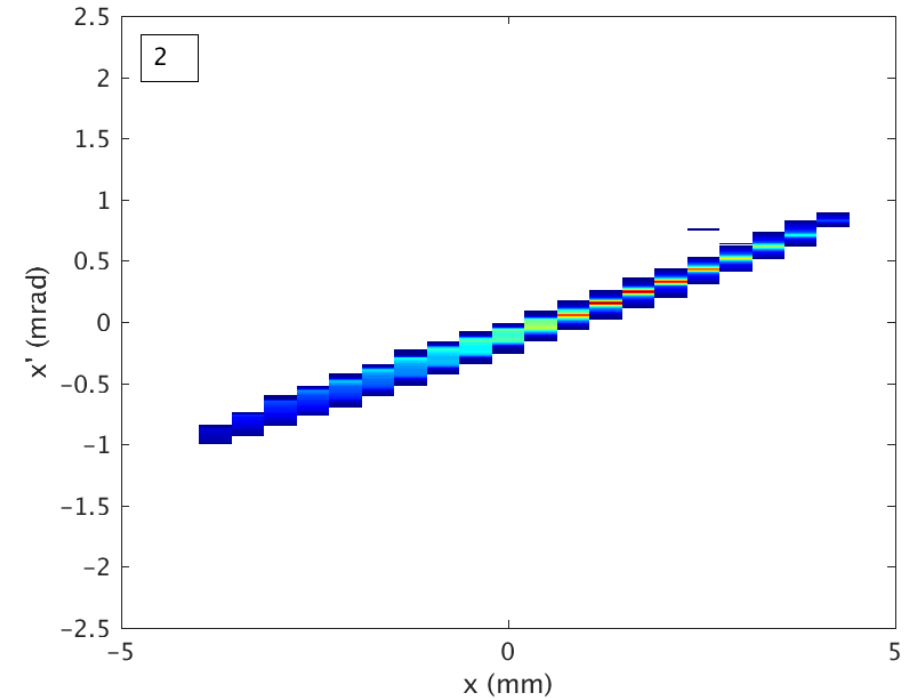
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RMS of ten emittances as error: $\frac{\Delta\epsilon}{\epsilon} = 3.7 \%$

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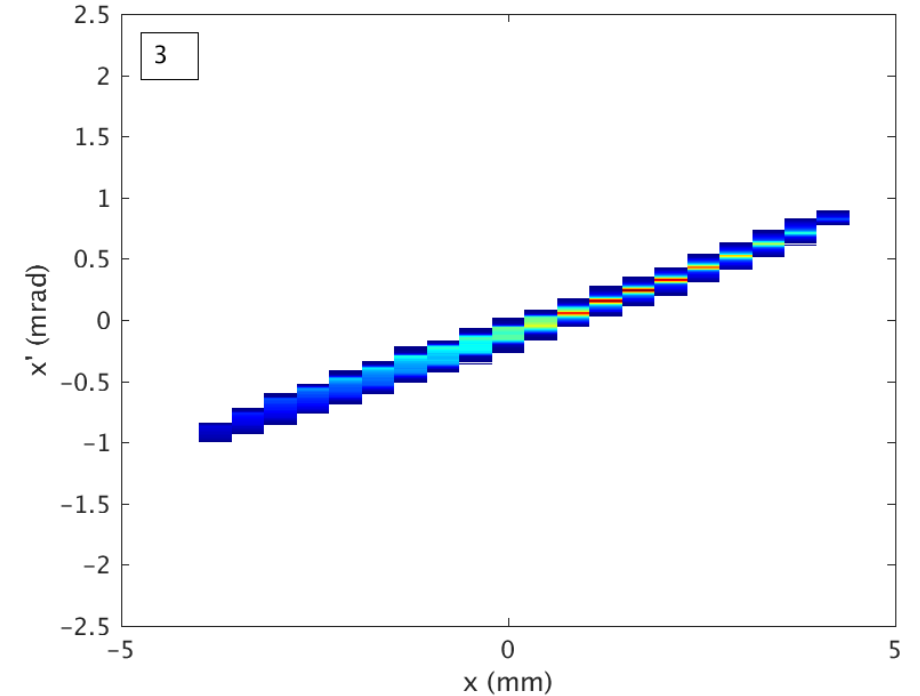
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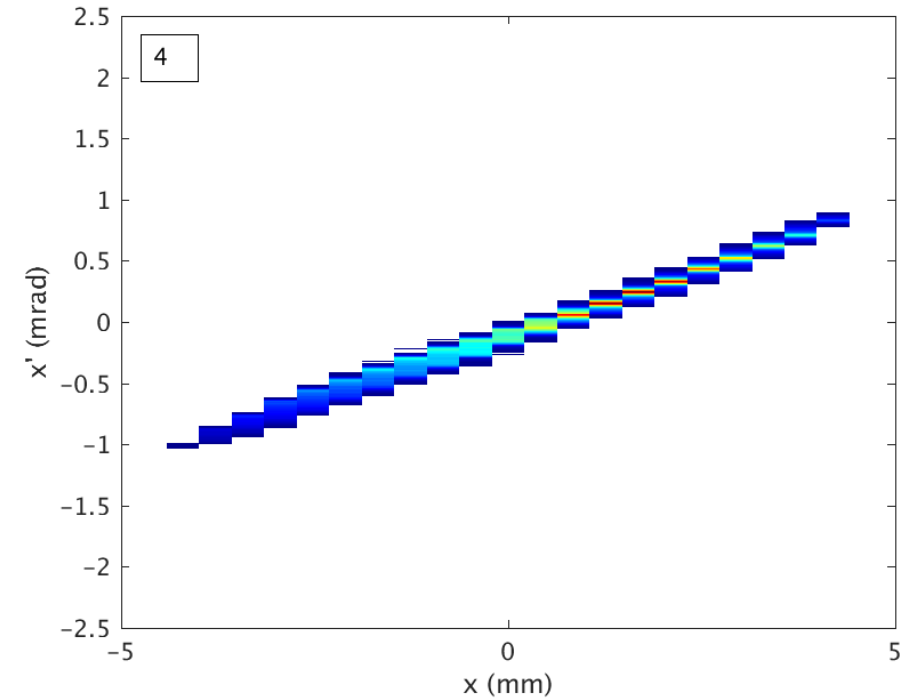
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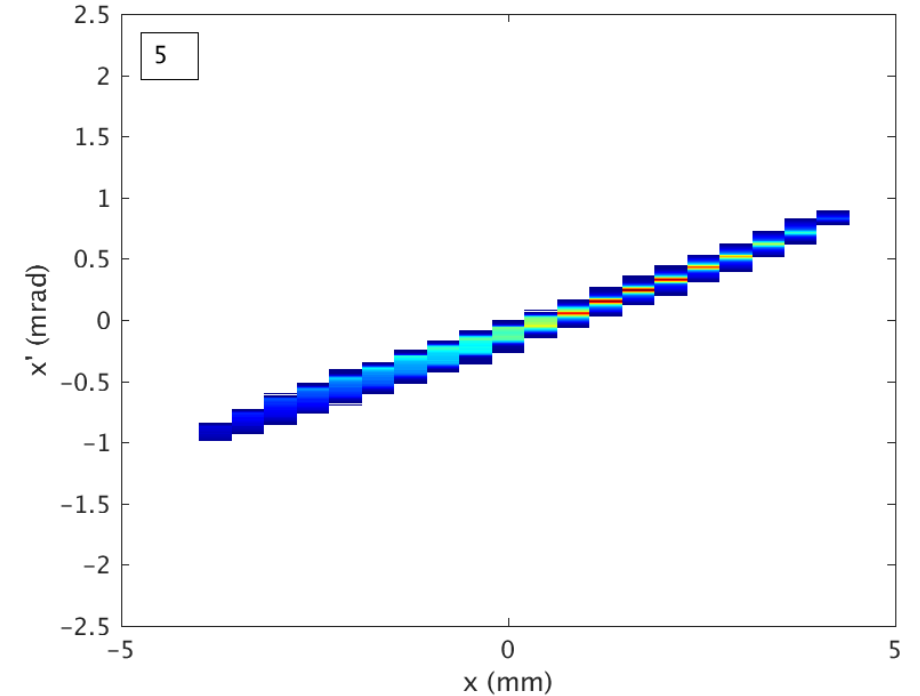
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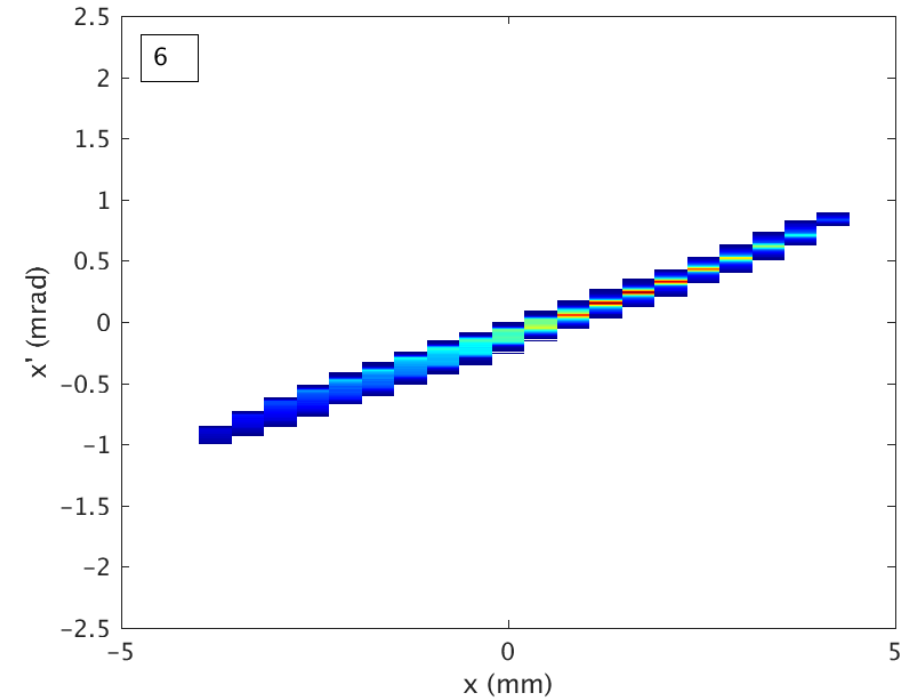
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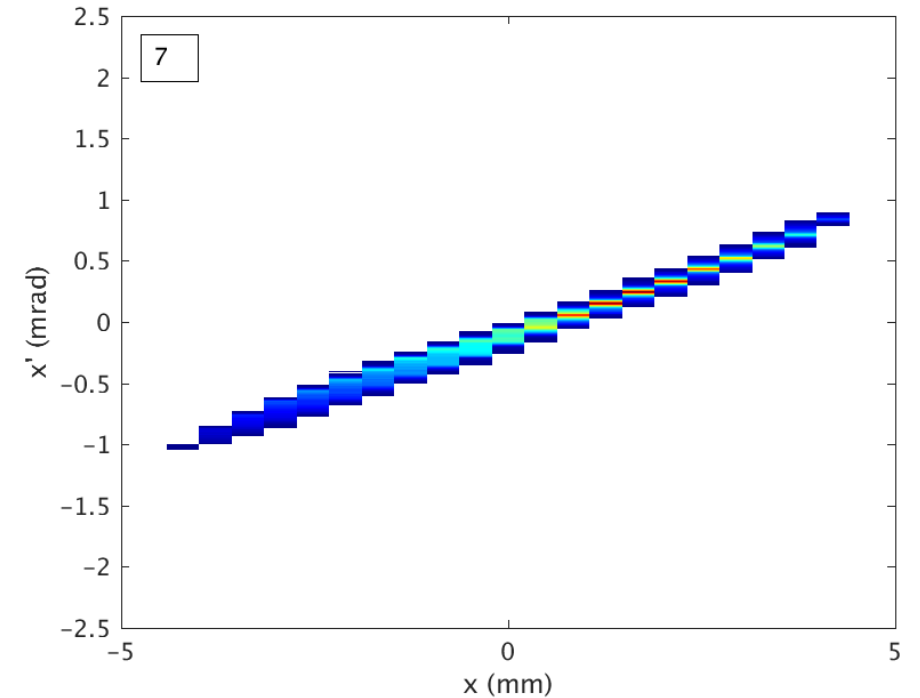
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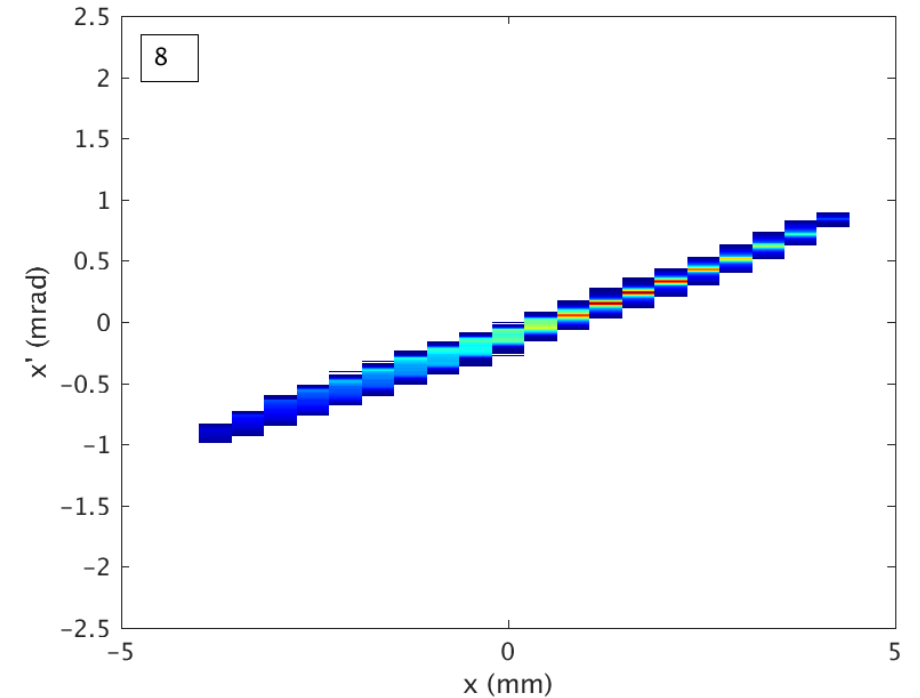
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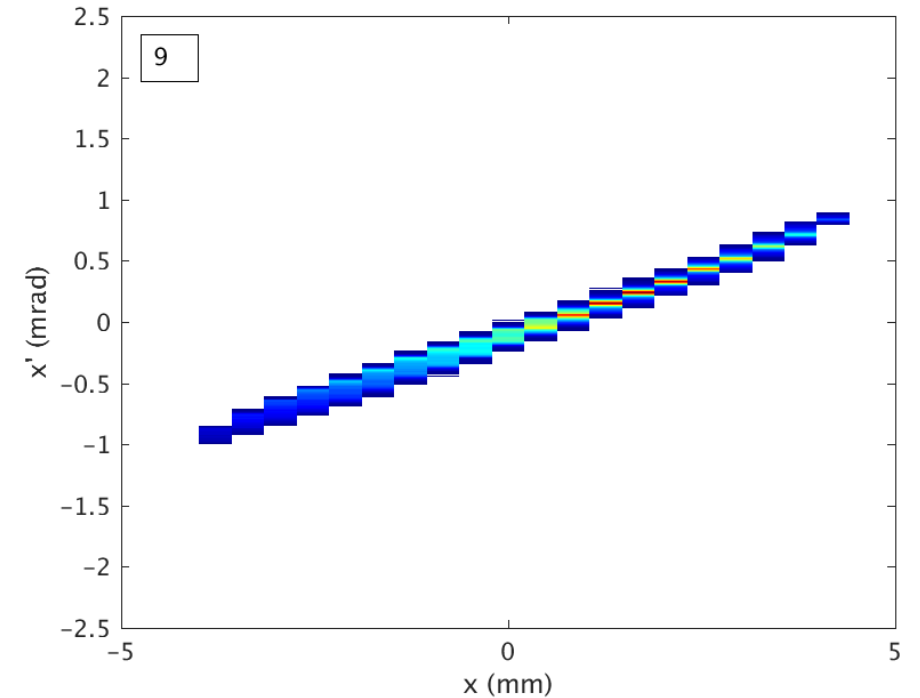
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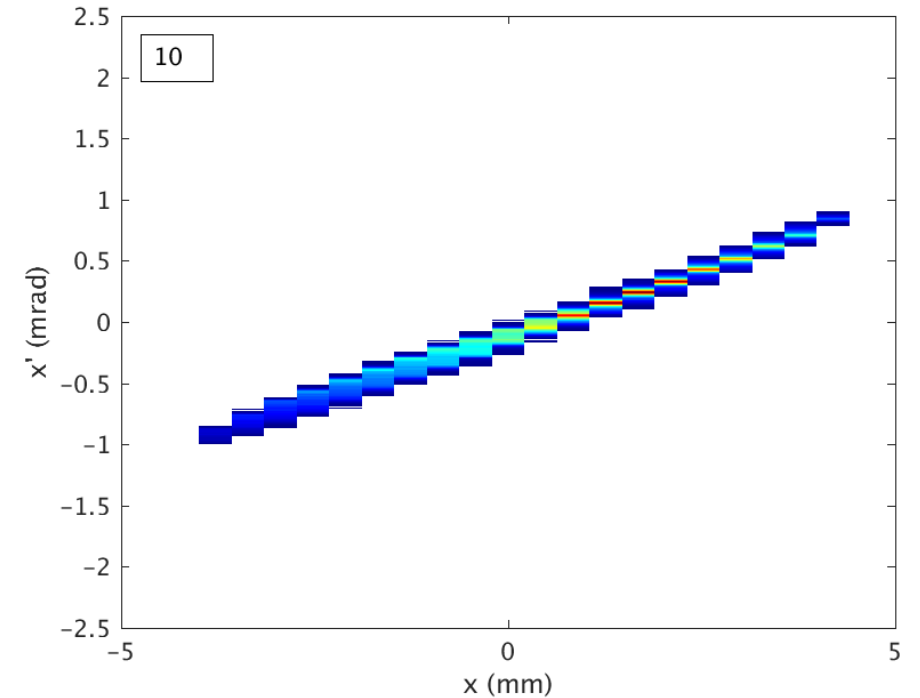
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